

Lecture II

Last week: Intro - examples
 - 3 of our main results

Today: Manifolds; • smth \leftrightarrow top \leftrightarrow PL
 • other dimensions
 • Handle decompositions

§. 2 Manifolds and handle decompositions

§. 2.1 Smooth manifolds

Def: A topological manifold is a second countable, Hausdorff topological space M which is locally Euclidean, i.e. $\forall p \in M \exists U \subset M$ open & \exists homeo $\varphi: U \xrightarrow{\cong} V$

where

- $V \subset \mathbb{R}^n$ open or
- $V \subset \mathbb{R}_+^n$ open. $\{x_n \geq 0\}$

$\leadsto (U, \varphi)$ chart at p

$\forall p \neq q$
 $\exists U, V \subset M$
 open, disj.
 s.t. $p \in U, q \in V$

Ex: $\mathbb{R}^n, \{B_r(x) \mid x \in \mathbb{Q}^n, r \in \mathbb{Q}_+\}$ = $\{B_i\}$ countable, $B_i \subset M$ open s.t.
 $\forall U \subset M$ open $U = \bigcup_{i \in I} B_i$

n : = dimension of M . [welldef'd: inv. of domain]

A smooth structure on M is a maximal (w.r.t inclusion) smooth collection of charts \downarrow
 atlas $\mathcal{A} = \{(U_i, \varphi_i)\}_{i \in I}$ for M , i.e. $\bigcup_{i \in I} U_i = M$ & any two

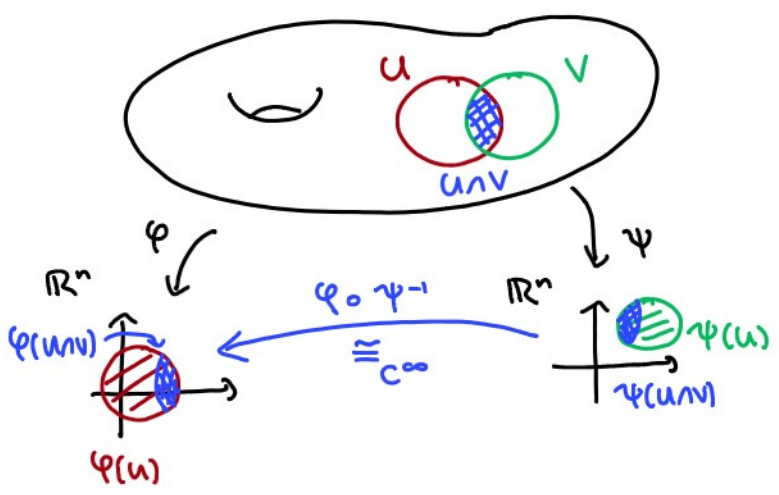
charts $(U, \varphi), (V, \psi) \in \mathcal{A}$ are smoothly compatible:

$\varphi \circ \psi^{-1}: \psi(U \cap V) \xrightarrow{\cong} \varphi(U \cap V)$ is a diffeomorphism.

\uparrow $\mathbb{R}^n \dashrightarrow \mathbb{R}^n$

transition map

\hookrightarrow smooth, bij. map w/ smooth inverse
 (as map $\mathbb{R}^n \rightarrow \mathbb{R}^n$, so all component fcts have cont. partial derivatives of all orders)



drop from notation \uparrow
 $\leadsto M$ (together w/ \mathcal{A}) is a smooth manifold.

~ • boundary $\partial M = \{p \in M \mid \exists (U, \varphi) \text{ boundary chart at } p, \text{ where } \varphi(U) = V \subset \mathbb{R}^n_+ \text{ open \& } \varphi(x) \in \partial \mathbb{R}^n_+\}$

• interior $\text{Int}(M) = \{p \in M \mid \exists (U, \varphi) \text{ interior chart at } p, U \subset \mathbb{R}^n \text{ open}\}$



If $\partial M \neq \emptyset$, we call M a manifold w/ boundary.

A compact mfd M w/ $\partial M = \emptyset$ is closed.

Ex: • A surface is a mfd of dim. 2.

• We've seen many smooth 3-mfds last week.

Reference for smooth mfds: [Lee, Introduction to smooth manifolds].

A map $f: M \rightarrow N$ between smooth mfds M, N is smooth if \forall charts (U, φ) of $M, (V, \psi)$ of N , the map $\psi \circ f \circ \varphi^{-1} \in C^\infty$ wherever it is defined.

Exer: draw corresponding schematic.

A diffeomorphism $M \rightarrow N$ is a smooth map w/ a smooth inverse.

⚠ For us, "manifold" will mean smooth manifold.
(from now on) ["mfd" = smooth mfd; top mfds, ...]

§ 2.2 Perspectives on manifolds

In the definition of a smooth manifold, we could ask the transition maps $\varphi \circ \psi^{-1}$ to be

- C^r ($C^0 = \text{top. mfd}$)
- biholomorphic (if $2 \ln$)
- \vdots
- isometries on e.g. $\mathbb{R}^n, \mathbb{H}^n, S^n$

→ additional geometric structure

↳ important e.g. for $n=3$:

Thurston's Geometrization Conj.

(Perelman 2003)

- PL = "piecewise linear"
(between open sets of \mathbb{R}^n)

[\rightarrow restriction of a simplicial map
def'd on polyhedron of some simplicial cx]

PL manifolds admit a triangulation, [PL \Rightarrow triangulable]

i.e. can be represented as geometric realization of a 3-dimensional simplicial complex.

[\exists simplicial cx $X =$ finite collection of simplices
s.t. faces of simplices are simpl. & intersections of simpl.
are faces of both simpl or \emptyset ; union of all simpl. $\rightarrow |X|$;
 M triangulated by X if \exists homeo $|X| \xrightarrow{\cong} M$]



$n=3$:



3-simplex \rightarrow building block of 3D simpl. cx.
= tetrahedron

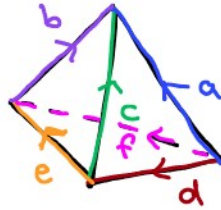
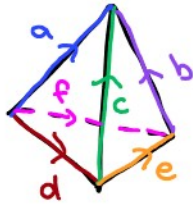
Thm (Bing, Moise '50s):

Every compact topological 3-mfd admits a triangulation

& has a PL structure.

Ex:

S^3 :



Thm (Munkres '60):
also Whitehead '61

Every compact topological 3-mfd has a unique
smooth structure (up to diffeomorphism).

$(M, A) \cong (M, B)$

See also [Thurston, Three-dimensional Geometry and Topology, Section 3.10].

Rem:

DIFF \subseteq PL \subseteq TOP
(category of smooth mfd's) \swarrow Whitehead '40

[TRIANG \nrightarrow PL
Ex: double suspension of Poincaré homology sphere]

$n=1, 2, 3$: = =

But in general $\neq \neq$

$n=4$: DIFF = PL \neq TOP

($n \leq 6$: SMOOTH \subseteq PL)
[Hirsch-Mazur '74]

[See also [Munkres Elementary Differential Topology, Chapter II]

Examples of weird phenomena:

n=7 [Milnor '56]: S^7 has exotic smooth structures, [Kervaire-Milnor \Rightarrow 28 smooth structures]
 i.e. \exists smooth M^7 s.t. $M \cong_{C^0} S^7$, $M \not\cong_{C^\infty} S^7$.

n=4: \exists uncountably infinitely many smooth structures on \mathbb{R}^4 .
 [Gompf, Taubes '80s
 '83, '85 '87]

In contrast, if $M^n \cong_{C^0} \mathbb{R}^n$, then $M \cong_{C^\infty} \mathbb{R}^n$.

Poincaré Conjecture

(goes back to Conj. by Poincaré 1904)

Henri Poincaré, French "universalist" 1854-1912

homotopy equivalent

Let M^n be a closed mfd, top. or smooth (TOP/DIFF),

s.t. $M \cong_{C^0/C^\infty} S^n$.

[Short version in TOP: Homotopy spheres are homeomorphic to spheres.]

TOP

Diff

YES!

\hookrightarrow maybe :)

- n=1 \checkmark
- n=2 \checkmark classif. of surf.
- n=3 Perelman 2003

- n=1,2,3 **YES!**
- n=7 **NO!** Milnor 1956
- n \geq 5 mostly well-understood

[Ricci flow, Hamilton, ... long history: Poincaré

$H_k(p)$ / homology sphere, Whitehead mfd, ...
 $= H_k(S^3)$
 $|\pi_1(p)|=120$
 open, contractible M^3 , noncpt, $M^3 \not\cong_{C^0} \mathbb{R}^3$, $\partial M = \emptyset$

[true for n=5,6,12,56,61]

n=4 Open!

- n=4 Freedman 1982; book "Disk Emb. Thm" (editors: Behrens-Kalmar-Kim-Powell-Ray '21)
- n \geq 5 Smale 1960

\hookrightarrow handle decompositions!

§ 2.3 Handle decompositions

Let M^n be a (smooth!) manifold.

Def: For $0 \leq k \leq n$, an n -dimensional k -handle h is a copy of $D^k \times D^{n-k}$, attached to M via an embedding (diffeo onto its image)

$$\varphi: \partial D^k \times D^{n-k} \hookrightarrow \partial M.$$

Ex: $k=0$: A 0-handle is $D^0 \times D^{n-k}$ attached along

$$\varphi: \partial D^0 \times D^n = \emptyset, \text{ so just disjoint union w/ } D^n.$$

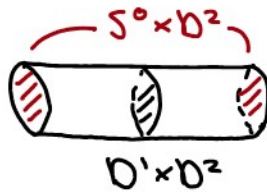
$n=3$

$k=0$:



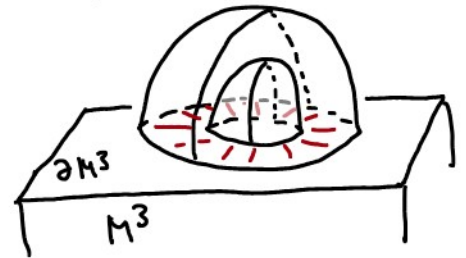
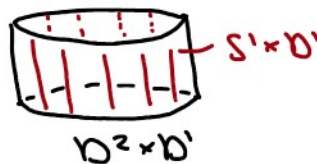
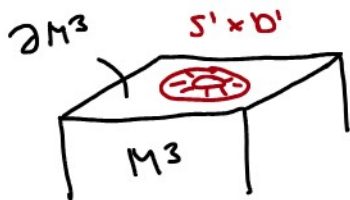
$k=1$:

1-handle $D^1 \times D^2$ att. along $\varphi: \partial D^1 \times D^2 \hookrightarrow \partial M$
 $= S^0 \times D^2 = \{-1, 1\} \times D^2 \subset \mathbb{R}^3$



$k=2$:

2-h. $D^2 \times D^1$ att. along $\varphi: \partial D^2 \times D^1 \hookrightarrow \partial M$
 $= S^1$



cylinder attached along annular part of its boundary

$k=3$:

3-h is $D^3 \times \{0\}$ att. along $\varphi: \partial D^3 \times \{0\} \hookrightarrow \partial M$
 $= S^2$



fill in S^2 in ∂M

[not possible if e.g.

$$M = S^1 \times D^2, \partial M = S^1 \times S^1]$$

Rem:

Note that $D^k \times D^{n-k} \cong_{\mathbb{C}^0} D^n$

$$\text{and } \partial(D^k \times D^{n-k}) = \partial D^k \times D^{n-k} \cup D^k \times \partial D^{n-k}.$$

\leadsto we're really gluing n -balls along parts of their boundary

Def:

For an n -dim. k -handle h_k attached to M via $\varphi: \partial D^k \times D^{n-k} \hookrightarrow \partial M$,

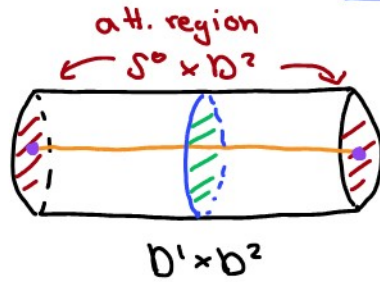
$\partial D^k \times D^{n-k}$ (or $\varphi(\partial D^k \times D^{n-k})$) is called attaching region

$D^k \times \{0\}$ is called Core

$\partial D^k \times \{0\}$ -"- attaching sphere

$\{0\} \times D^{n-k}$ -"- Cocore

$\{0\} \times \partial D^{n-k}$ -"- belt sphere



core $D^1 \times \{0\}$ w/ att. sph. $S^0 \times \{0\}$ as bdy

Rem:

View/ think of $M \cup_\varphi h$ as smooth manifold.

\leadsto actually mfd with corners, but can "straighten" them (in any dimension!) \downarrow



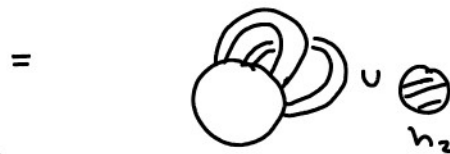
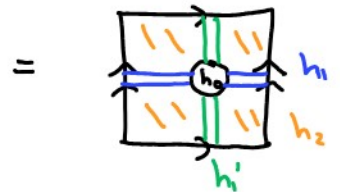
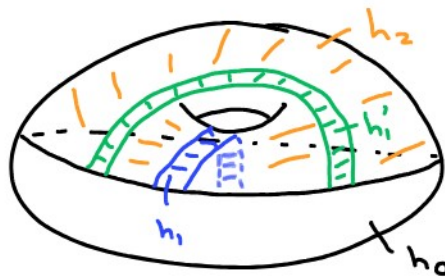
[Wall, Differential Topology, §2.6]

in dim $n=3$: $\exists!$ smooth structure (see above)

Ex:

$S^n = \text{circle} = D^n \cup D^n = h_0 \cup h_n$

$T^2 = S^1 \times S^1$



$\mathbb{R}P^2 = \text{circle with handle} \cup h_2$

$S^2 = \text{hemisphere} \cup \text{hemisphere} \cup h_0$

\leadsto handle decompositions not unique

Def: $\varphi_0, \varphi_1 : Y \hookrightarrow X$ embeddings are isotopic if \exists smooth homotopy $h : Y \times I \rightarrow X$ through embeddings, i.e. $h_t : Y \rightarrow X$ is an emb. $\forall 0 \leq t \leq 1$.
 $h_t(\cdot) = h(\cdot, t), h_0 = \varphi_0, h_1 = \varphi_1$

Thm (Isotopy Extension Theorem) [Wall, Thm 2.4.2] [Kosinsky, Thm 5.2 in Chapter II]
 (Thom, Cerf, Palais) [Hirsch, §8.1]

Y, X compact & $h : Y \times I \rightarrow X$ isotopy of embeddings $Y \hookrightarrow X$
 $\Rightarrow \exists H : X \times I \rightarrow X$ smooth map s.t.

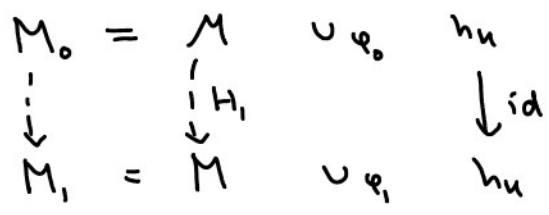
- $H_0 = id_X$
 - $H_t : X \rightarrow X$ ($H_t(\cdot) = H(\cdot, t)$) diffeo $\forall 0 \leq t \leq 1$
 - $h_t = H_t \circ h_0 \quad \forall t$ [Pf idea: vector fields]
- } ambient isotopy [or diffeotopy]

(locally flat)
 [top. version due to Edwards-Kirby]

Lemma: $\varphi_i : \partial D^k \times D^{n-k} \hookrightarrow \partial M, i=1,2$ isotopic embeddings] will repeat in Lect. 3
 $\Rightarrow M \cup_{\varphi_1} h_u \cong_{C^\infty} M \cup_{\varphi_2} h_u$

Pf: Extend an isotopy $h = \varphi_t$ to an ambient isotopy $H : \partial M \times I \rightarrow \partial M$ using the Isotopy Extension Theorem.

Use this to find a diffeo $M_0 \xrightarrow{\quad} M_1 :$

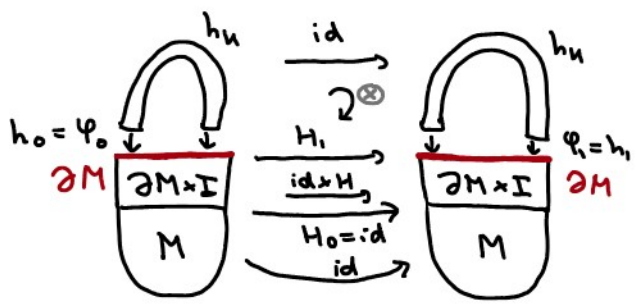


To make this more precise, consider the diffeo

$$H \times Id_I : \partial M \times I \rightarrow \partial M \times I$$

Now, identify $\partial M \times I$ w/ a collar neighborhood of ∂M in M , i.e. a nbhd of ∂M in M diffeom. to $\partial M \times I$ s.t. ∂M is identified w/ $\partial M \times \{0\}$.
 [or, put differently, an emb. $\partial M \times I \hookrightarrow M$ ext. $\partial M \times \{0\} \rightarrow \partial M$ proj.]

Schematic:



$$\otimes H_1 \circ h_0 = h_1 \circ id$$

\otimes Lemma: For every mfd w/ bdry, the bdry has a collar nbhd. [Wall, Differential Topology, Thm 1.5.5]
 [Pf idea: vector fields]